

The main challenges of Brain-computer interfaces: reliability and usability

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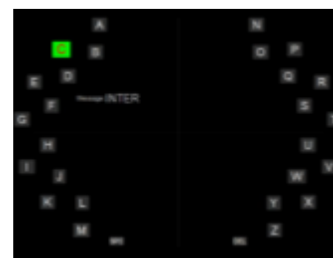
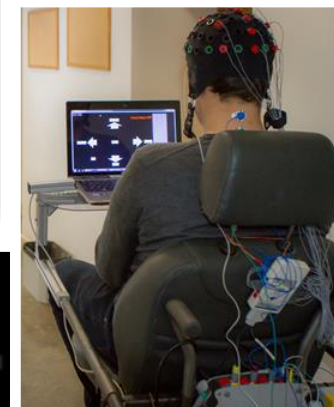
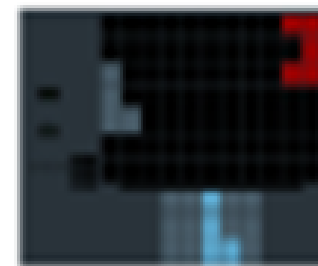


Context

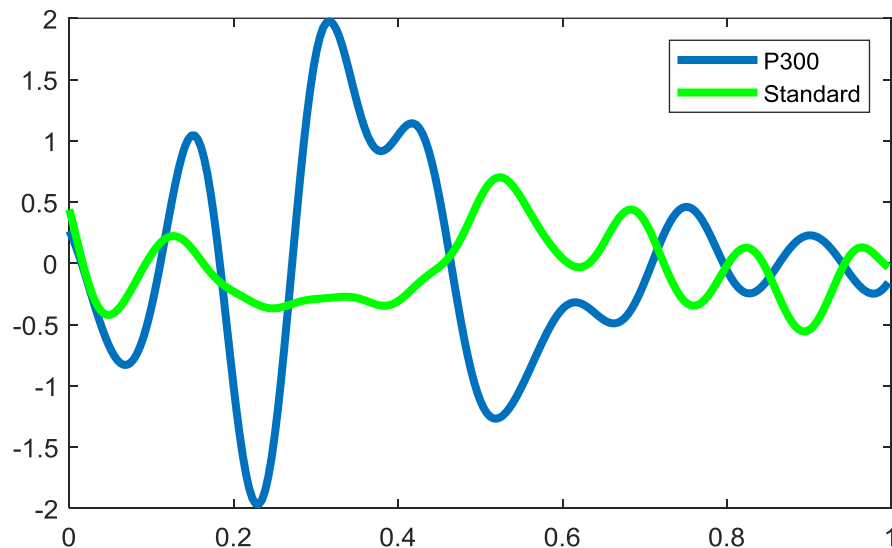
Brain-computer interface (BCI) is an emerging technology with successful applications for both healthy and disabled individuals.

Major EEG-based BCIs challenges:

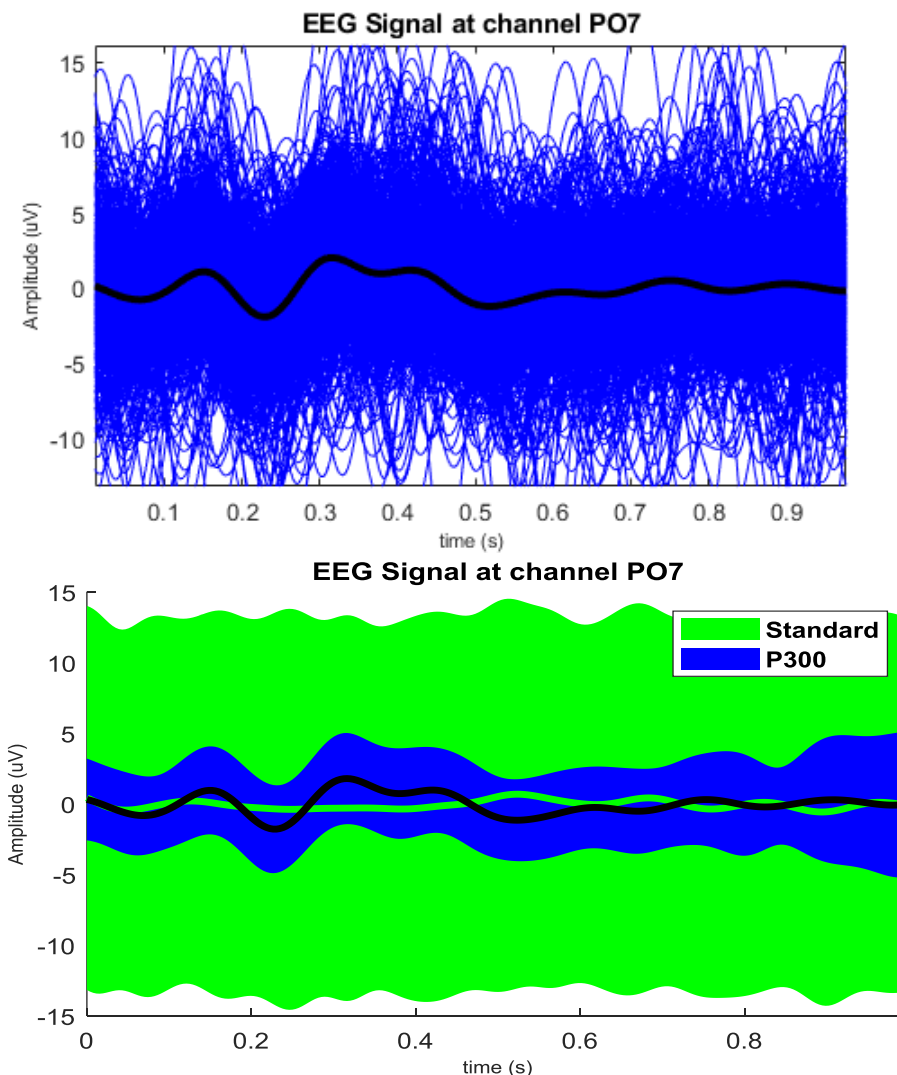
- EEG signal has low Signal-to-noise ratio (SNR);
- Great variability within and across subjects;
- High level of concentration and attention;
- Low reliability and usability.



Context



Current BCIs systems have low reliability in recognizing the subject's intent.



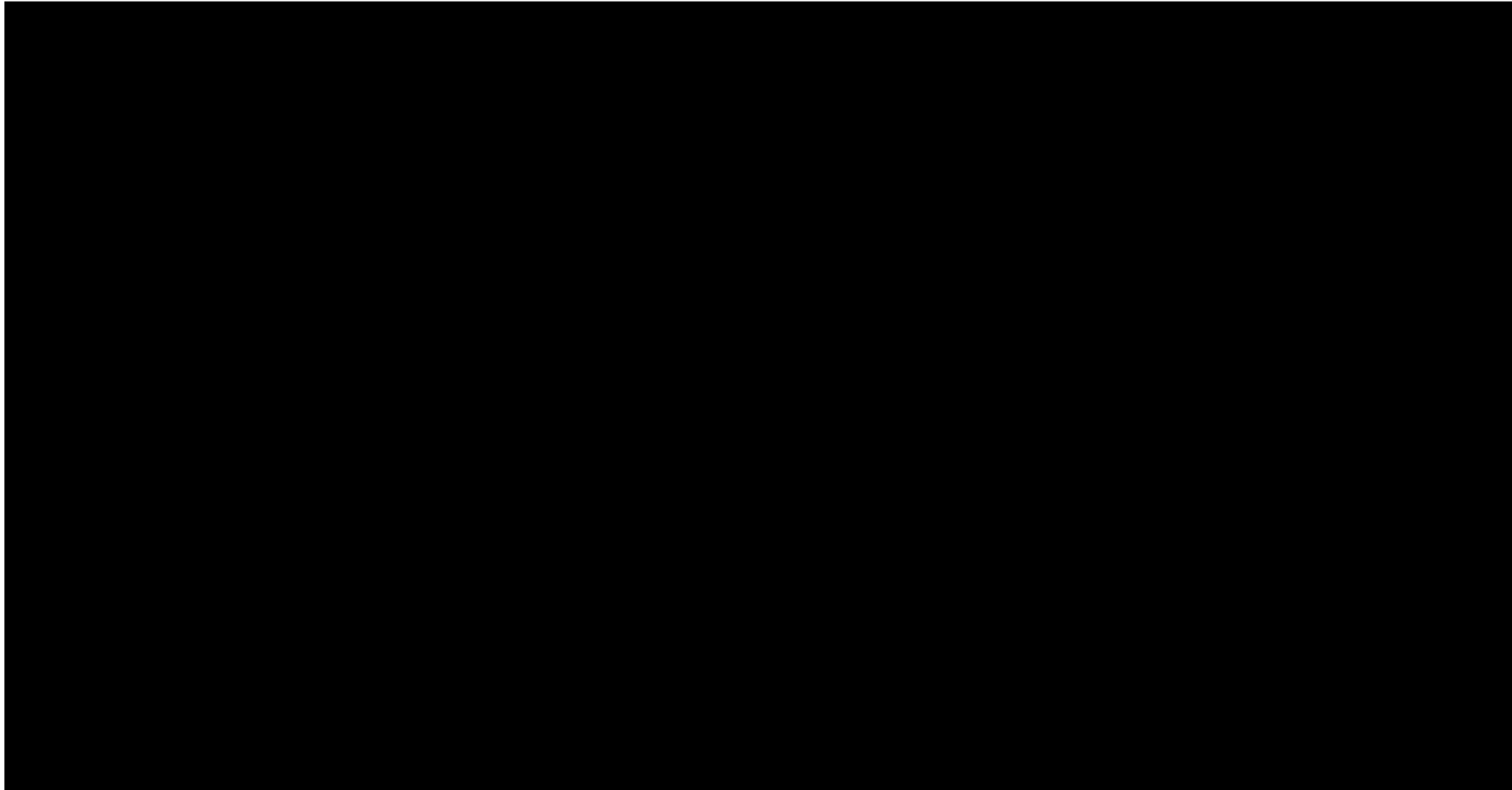
Error-Related Potential (ErrP): Double Detection Approach

The ErrP is an event-related potential generated naturally in the brain when a person perceives a mistake.

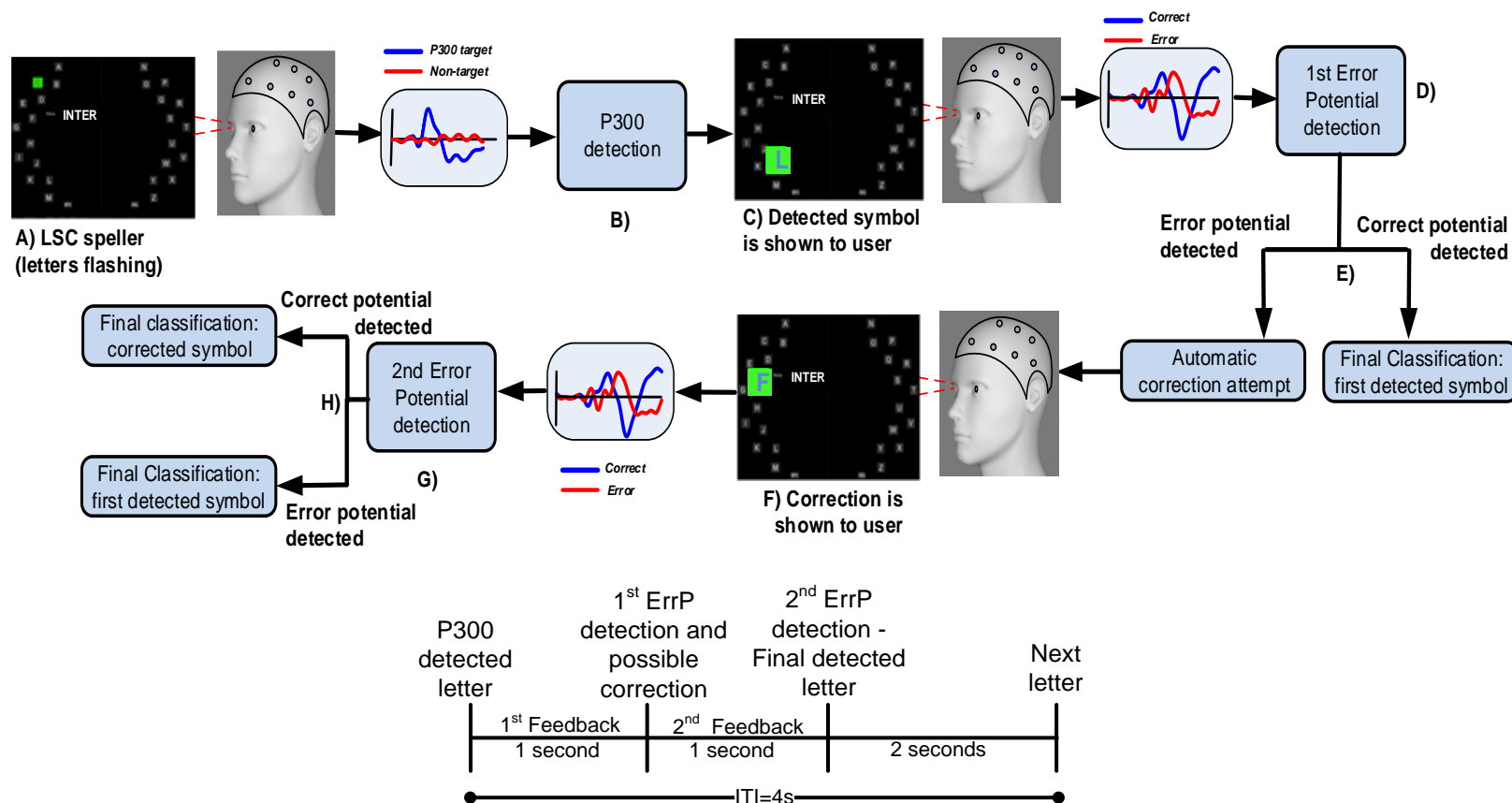
The main goal of this approach:

- Automatic detection of error-related potentials (ErrPs) in order to increase the reliability and transfer rates of brain-machine interfaces.
- The use of ErrPs in a closed-loop, allowing the user to change or confirm system decisions.

On-line operation: demonstrative video



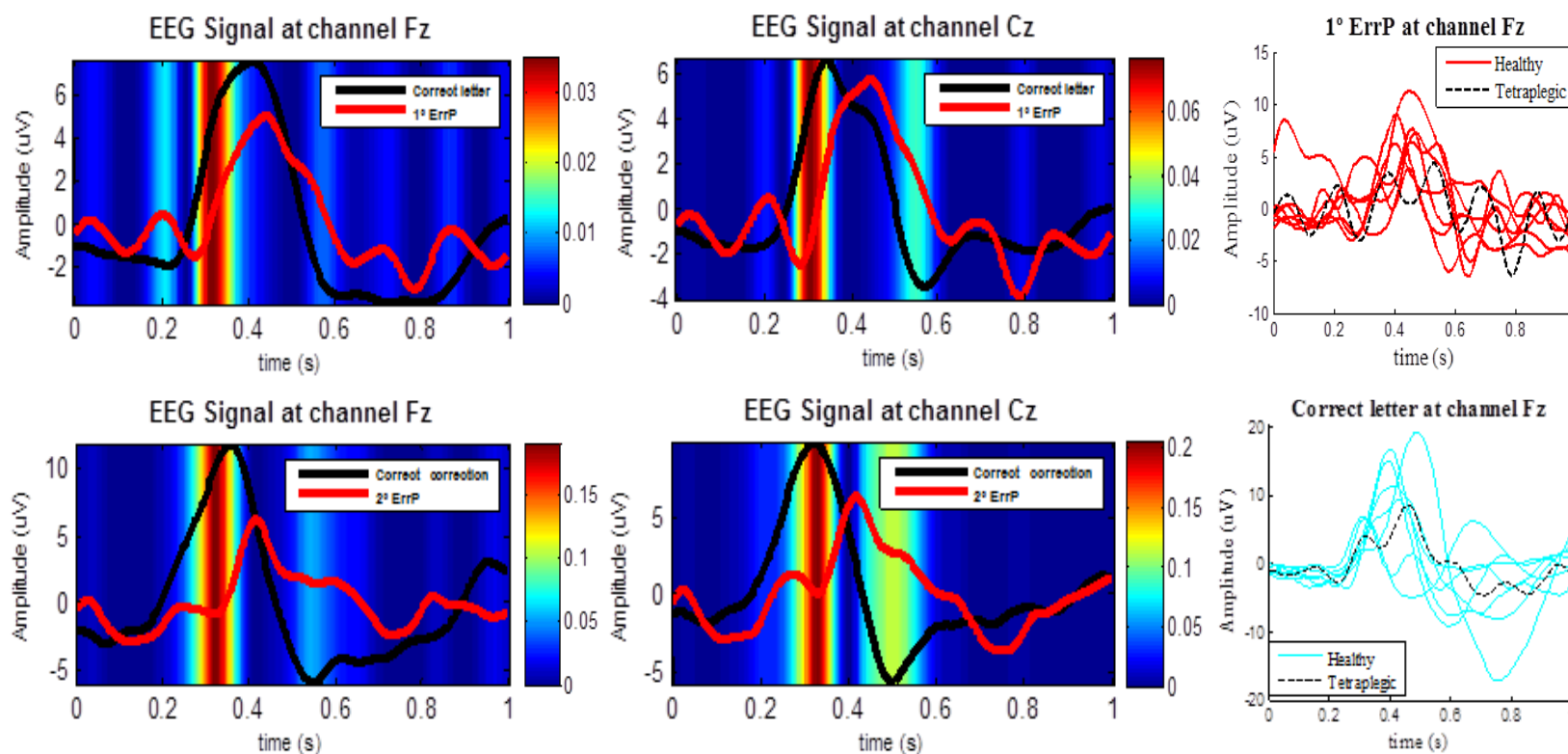
Double ErrP Detection Approach



Double ErrP detection:

- Use the information of 1st ErrP to perform the automatic correction;
- Use the information of 2nd ErrP to confirm the correction.

Evoked potentials after correct and wrong feedbacks



- The positive feedback is different from the ErrP.
- The waveform of 1st and 2nd ErrP is slightly different.

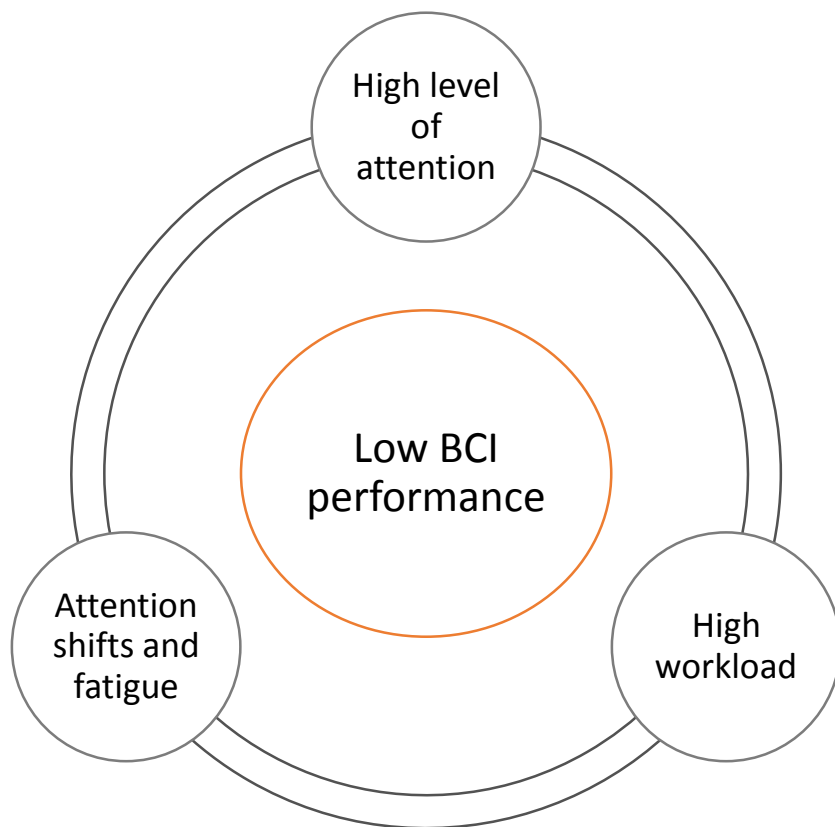
Online classification performance

		Pre-Acc (%)	Post-Acc (%)	Pre-ITR (bpm)	Post-ITR (bpm)	Pre-B _{ECS} (bpt)	Post-B _{ECS} (bpt)	Pre-eSPM	Post-eSPM	Acc-ErrP ₁ (%)	Acc-ErrP ₂ (%)	N _{rep}
Subjects	S1	81,6	92,8	9,87	12,45	3,00	3,57	1,92	2,6	90,8	86,1	7
	S2	93,2	94,7	15,96	16,49	4,10	4,20	3,34	3,46	96,3	81,3	5
	S3	93,2	96,3	15,96	17,05	4,10	4,25	3,34	3,59	89,5	90,9	5
	S4	84,7	89,5	11,81	13,03	3,30	3,60	2,37	2,69	75,8	80,0	6
	S5	73,7	79,6	8,30	9,47	2,25	2,66	1,44	1,8	92,1	78,6	7
	S6	95,8	95,8	14,85	14,85	4,35	4,35	3,12	3,12	76,3	92,2	6
	S9	81,1	90,5	17,02	20,73	2,95	3,50	3,3	4,3	96,8	85,0	3
	P1	75,0	79,6	8,55	9,47	2,38	2,63	1,52	1,8	89,5	84,8	7
	Mean	84,8	89,9	12,79	14,19	3,31	3,60	2,54	2,92	88,4	84,8	5,80
Difference		5,1		1,4		0,29		0,38				

- The proposed approach increased the accuracy of 5.1%.
- The 1st and 2nd ErrP were successfully detected at a single level.

Usability of BCI

Towards User-friendly Brain-controlled Wheelchair



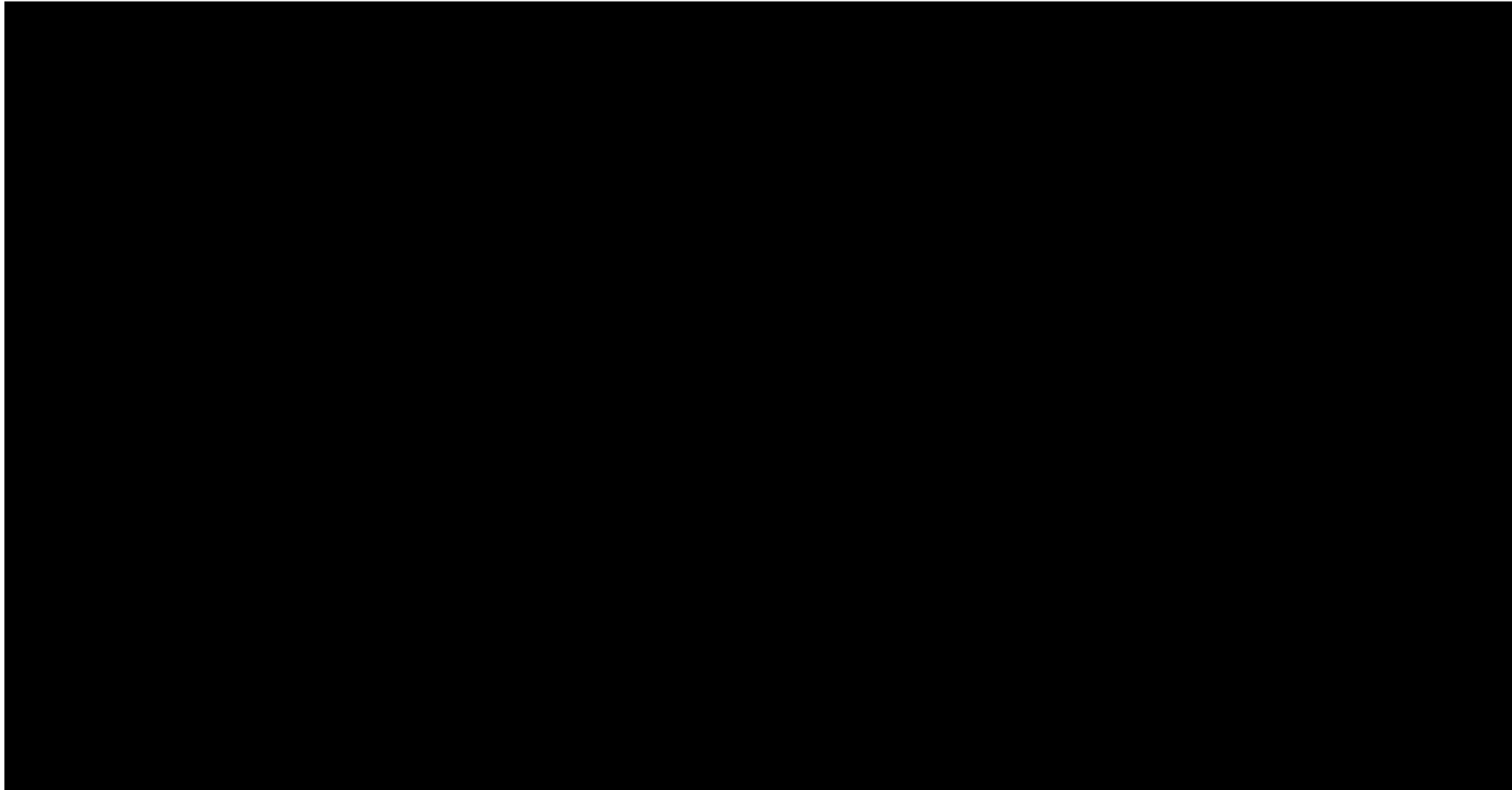
➤ We propose a minimum-effort brain-controlled wheelchair that combines:

1. collaborative control;
2. self-paced control;
3. dynamic time trial.

Towards User-friendly Brain-controlled Wheelchair

- **Self-paced control:** allows the user to issue a command only if he/she desires and the BCI detects whether the user is in a control state or in a non-control state.
- **Self-paced approach with static trial:** uses a fixed number of stimuli sequences.
- **Dynamic time trial approach:** automatically sets the number of stimuli sequences according to user's context awareness.
- **Collaborative-control:** validates user's command according to the navigation context.

Demonstrative video



Online BCW performance

Subjects	Task1: self-paced mode with static trial					Task3: non-self-paced mode with static trial-time			
	CC	NCC	TT	Acc_BCI (%)	Acc_BCW (%)	CC (%)	Acc_BCI (%)	Acc_BCW (%)	
S1	8	61	7,1	95,7	100,0	85	75,3	88,2	
S2	12	72	5,9	97,6	100,0	73	97,3	97,3	
S3	11	58	7,1	100,0	100,0	65	93,8	93,8	
S5	10	78	7,1	100,0	100,0	71	94,4	94,4	
S6	10	66	7,1	97,4	100,0	85	91,8	96,5	
S8	7	57	8,4	96,9	100,0	62	82,3	95,2	
S9	14	49	7,1	92,1	100,0	71	88,7	97,2	
Average	10,3	63,0	7,1	97,1	100,0	73,1	89,1	94,6	
P1	14	63	7,1	92,2	98,7	-	-	-	
P3	23	104	7,1	94,5	100,0	-	-	-	
P4	13	85	7,1	93,9	100,0	-	-	-	
P7	13	68	7,1	91,4	98,8	-	-	-	
P8	17	77	5,9	98,9	100,0	-	-	-	
P9	12	66	7,1	97,4	100,0	-	-	-	
Average	15,3	77,2	6,9	94,7	99,6				

➤ **The self-paced control enormously reduced the number of control commands, the user's workload, and consequently, it increased the BCI accuracy in 8.0%.**

Online BCW performance

Task2: self-paced mode with dynamic trial (DTT)							
Subjects	CC	NCC	TT(Max)	TT(Min)	TT(Mean)	Acc_BCI (%)	Acc_BCW (%)
S1	7	27	5,9	4,7	5,5	97,1	97,1
S2	11	31	8,4	3,5	4,9	100,0	100,0
S3	14	27	9,6	5,9	6,7	100,0	100,0
S5	10	31	5,9	4,7	5,8	97,6	100,0
S6	19	30	9,6	5,9	6,4	89,8	100,0
S8	10	23	10,8	5,9	8,0	93,9	100,0
S9	41	23	8,4	4,7	6,3	82,8	96,9
Average	16	27,4	8,4	5,0	6,2	94,5	99,1
P1	9	33	7,1	7,1	7,1	95,2	100,0
P3	36	36	9,6	4,7	6,8	81,9	98,6
P4	9	31	9,6	5,9	7,1	97,5	100,0
P7	12	79	5,9	4,7	5,7	94,5	98,9
P8	13	50	4,7	3,5	4,4	100,0	100,0
P9	8	31	7,4	5,2	6,2	87,2	100,0
Average	14,5	43,3	7,4	5,2	6,2	92,7	99,6

- **With the DTT approach, BCI speed vs. user's performance is adjusted online.**
- **DTT reduced the time to select a command in about 1 s, although it decreased the BCI accuracy in about 2%.**

Conclusion

- **Low reliability and usability are the major drawbacks of current BCIs, which limit their use outside laboratories.**
- **Using the proposed double ErrP detection there was an improvement in the BCI online accuracy around 5%.**
- **The proposed approach that combines collaborative control, self-paced control, and dynamic-time commands was extremely effective with overall accuracy greater than 99% for both able-bodied and motor disabled participants.**

Publications

- **Cruz, A., Pires, G., Lopes, A., Carona, C., & Nunes, U. J. (2021). A self-paced BCI with a collaborative controller for highly reliable wheelchair driving: Experimental tests with physically disabled individuals. IEEE Transactions on Human-Machine Systems, 51(2), 109-119.**
- **Cruz, A., Pires, G., Lopes, A. C., & Nunes, U. J. (2019, July). Detection of stressful situations using GSR while driving a BCI-controlled wheelchair. In 2019 41st Annual international conference of the IEEE engineering in medicine and biology society (EMBC) (pp. 1651-1656). IEEE.**
- **Cruz, A., Pires, G., & Nunes, U. J. (2017). Double ErrP detection for automatic error correction in an ERP-based BCI speller. IEEE transactions on neural systems and rehabilitation engineering, 26(1), 26-36.**

Acknowledgments

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Thank you for your attention!